

The PASCAL Visual Object Classes Challenge 2010 (VOC2010)

Part 2 – Detection Task

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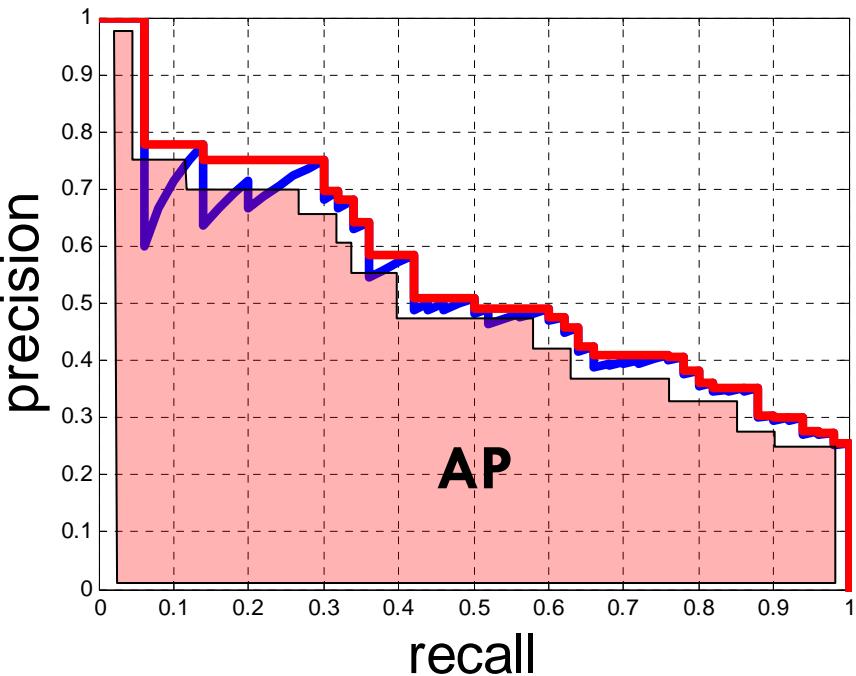
Detection Challenge

- Predict the bounding boxes of all objects of a given class in an image (if any)

- Competition 3: Train on the supplied data
 - Which methods perform best given specified training data?

- Competition 4: Train on any (non-test) data
 - How well do state-of-the-art methods perform on these problems?

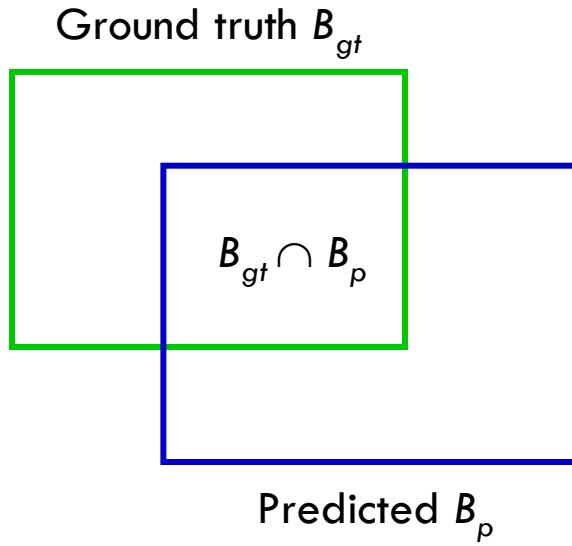
Average Precision: VOC2010



- Interpolate curve to create version for which the precision is monotonically non-increasing
- Measure area under interpolated curve
- Sawtooth shape is ignored
- Area is measured with maximum accuracy
- Good score requires both high precision **and** recall

Evaluating Bounding Boxes

- Area of Overlap (AO) Measure



$$AO(B_{gt}, B_p) = \frac{|B_{gt} \cap B_p|}{|B_{gt} \cup B_p|}$$

- Need to define a threshold t such that $AO(B_{gt}, B_p)$ implies a correct detection: 50%

Methods

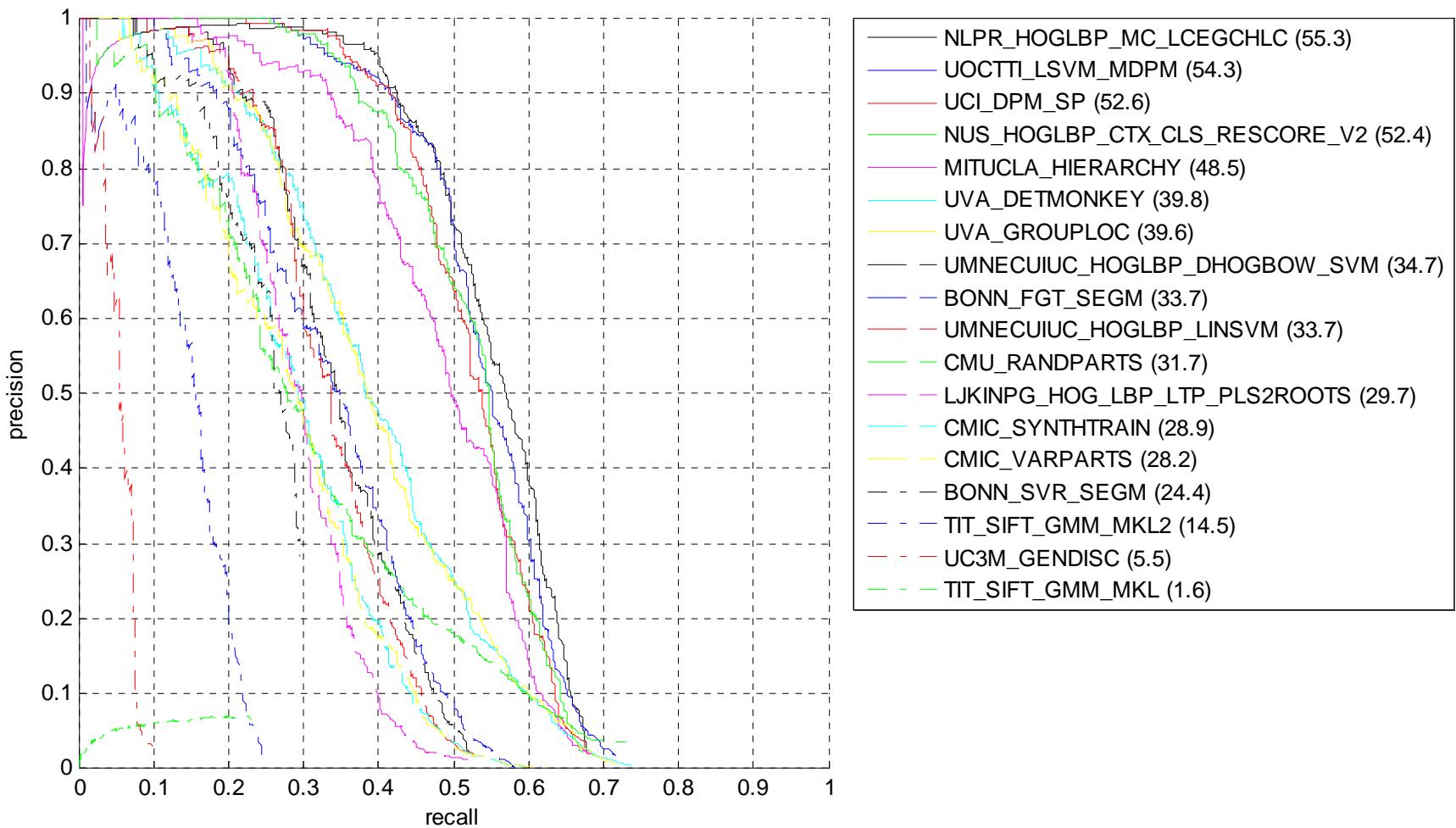
- 22 Methods, 15 Groups
 - VOC2009: 18 Methods, 12 Groups
- Methods
 - Sliding window, SVM, multiple features e.g. HOG, LBP
 - Parts-based models, hierarchical models
 - Segmentation-based object hypotheses (“jumping window”)
 - Combination with whole-image classification
- Use of external training data
 - Additional data (e.g. annotated with Mechanical Turk)
 - More detailed annotation e.g. parts

AP by Class/Method

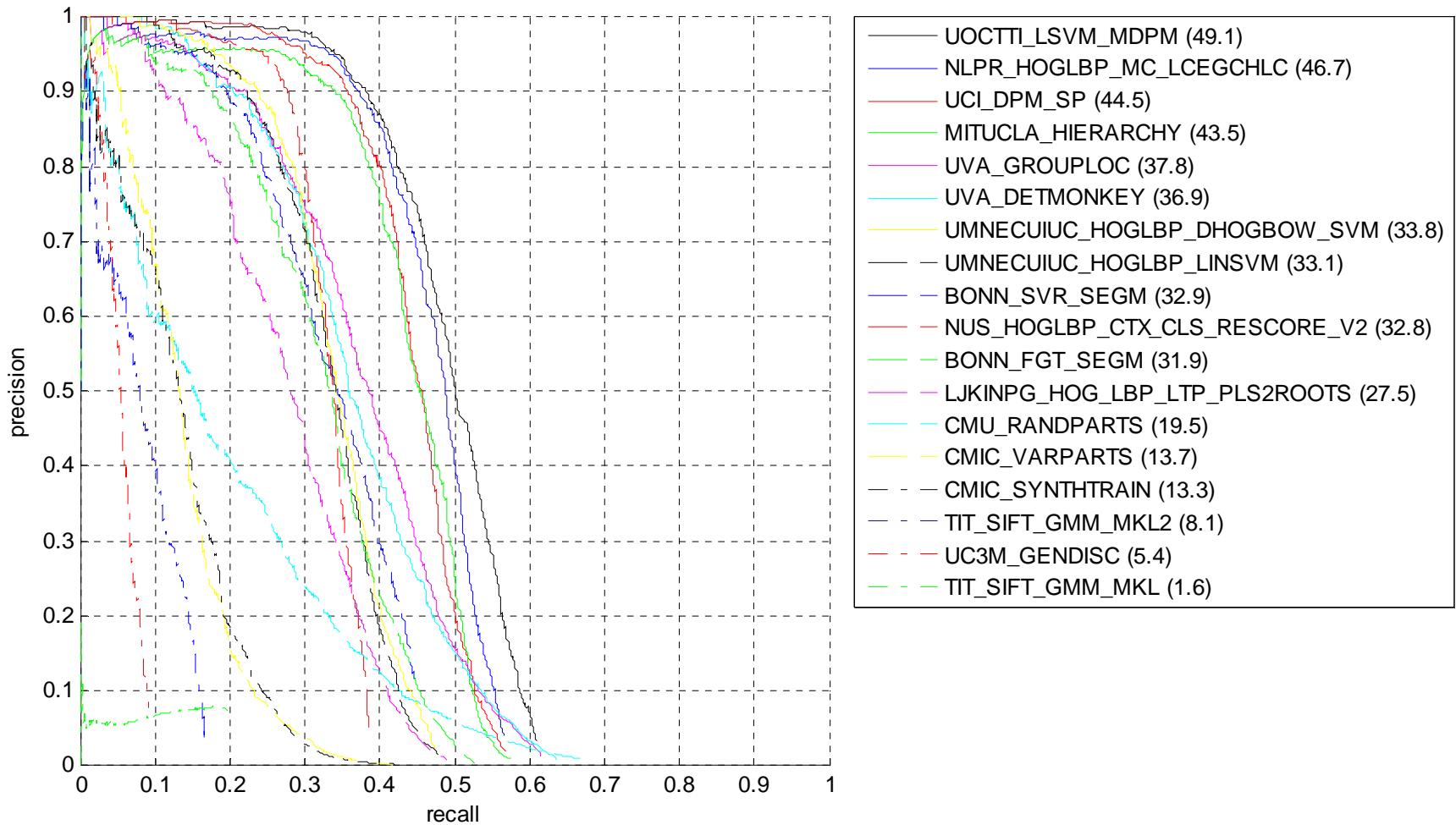
(1st, 2nd, 3rd place)

	aero plane	bicycle	bird	boat	bottle	bus	car	cat	chair	cow	dining table	dog	horse	motor bike	person	potted plant	sheep	sofa	train	tv/ monitor
BONN_FGT_SEGM	52.7	33.7	13.2	11.0	14.2	43.1	31.9	35.6	5.7	25.4	14.4	20.6	38.1	41.7	25.0	5.8	26.3	18.1	37.6	28.1
BONN_SVR_SEGM	50.5	24.4	17.1	13.3	10.9	39.5	32.9	36.5	5.6	16.0	6.6	22.3	24.9	29.0	29.8	6.7	28.4	13.3	32.1	27.2
CMIC_SYNTHTRAIN	-	28.9	-	-	-	30.2	13.3	-	-	-	-	-	26.2	28.1	13.2	-	-	-	18.8	25.7
CMIC_VARPARTS	-	28.2	-	-	-	26.9	13.7	-	-	-	-	-	23.5	24.7	16.1	-	-	-	18.8	24.5
CMU_RANDPARTS	23.8	31.7	1.2	3.4	11.1	29.7	19.5	14.2	0.8	11.1	7.0	4.7	16.4	31.5	16.0	1.1	15.6	10.2	14.7	21.0
CMU_RANDPARTS _MAXSCORE	-	-	2.7	-	-	-	-	16.2	-	10.6	8.5	-	-	-	17.9	-	-	-	15.7	-
LJKINPG_HOG_LBP _LTP_PLS2ROOTS	32.7	29.7	0.8	1.1	19.8	39.4	27.5	8.6	4.5	8.1	6.3	11.0	22.9	34.1	24.6	3.1	24.0	2.0	23.5	27.0
MITUCLA_HIERARCHY	54.2	48.5	15.7	19.2	29.2	55.5	43.5	41.7	16.9	28.5	26.7	30.9	48.3	55.0	41.7	9.7	35.8	30.8	47.2	40.8
NLPR_HOGLBP_MC _LCEGCHLC	53.3	55.3	19.2	21.0	30.0	54.4	46.7	41.2	20.0	31.5	20.7	30.3	48.6	55.3	46.5	10.2	34.4	26.5	50.3	40.3
NUS_HOGLBP_CTX _CLS_RESCORE_V2	49.1	52.4	17.8	12.0	30.6	53.5	32.8	37.3	17.7	30.6	27.7	29.5	51.9	56.3	44.2	9.6	14.8	27.9	49.5	38.4
TIT_SIFT_GMM_MKL	10.5	1.6	1.2	0.9	0.1	2.8	1.6	6.7	0.1	2.0	0.4	3.0	2.0	4.4	2.0	0.3	1.1	1.2	2.1	1.9
TIT_SIFT_GMM_MKL2	20.0	14.5	3.8	1.2	0.5	17.6	8.1	28.5	0.1	2.9	3.1	17.5	7.2	18.8	3.3	0.8	2.9	6.3	7.6	1.1
UC3M_GENDISC	15.8	5.5	5.6	2.3	0.3	10.2	5.4	12.6	0.5	5.6	4.5	7.7	11.3	12.6	5.3	1.5	2.0	5.9	9.1	3.2
UCI_DPM_SP	46.1	52.6	13.8	15.5	28.3	53.2	44.5	26.6	17.6	-	16.1	20.4	45.5	51.2	43.5	11.6	30.9	20.3	47.6	-
UMNECUIUC_HOGLBP _DHOGBOW_SVM	40.4	34.7	2.7	8.4	26.0	43.1	33.8	17.2	11.2	14.3	14.4	14.9	31.8	37.3	30.0	6.4	25.2	11.6	30.0	35.7
UMNECUIUC_HOGLBP _LINSVM	37.9	33.7	2.7	6.5	25.3	37.5	33.1	15.5	10.9	12.3	12.5	13.7	29.6	34.5	33.8	7.2	22.9	9.9	28.9	34.1
UOCTTI_LSVM_MDPM	52.4	54.3	13.0	15.6	35.1	54.2	49.1	31.8	15.5	26.2	13.5	21.5	45.4	51.6	47.5	9.1	35.1	19.4	46.6	38.0
UVA_DETMONKEY	56.7	39.8	16.8	12.2	13.8	44.9	36.9	47.7	12.1	26.9	26.5	37.2	42.1	51.9	25.7	12.1	37.8	33.0	41.5	41.7
UVA_GROUPLOC	58.4	39.6	18.0	13.3	11.1	46.4	37.8	43.9	10.3	27.5	20.8	36.0	39.4	48.5	22.9	13.0	36.8	30.5	41.2	41.9

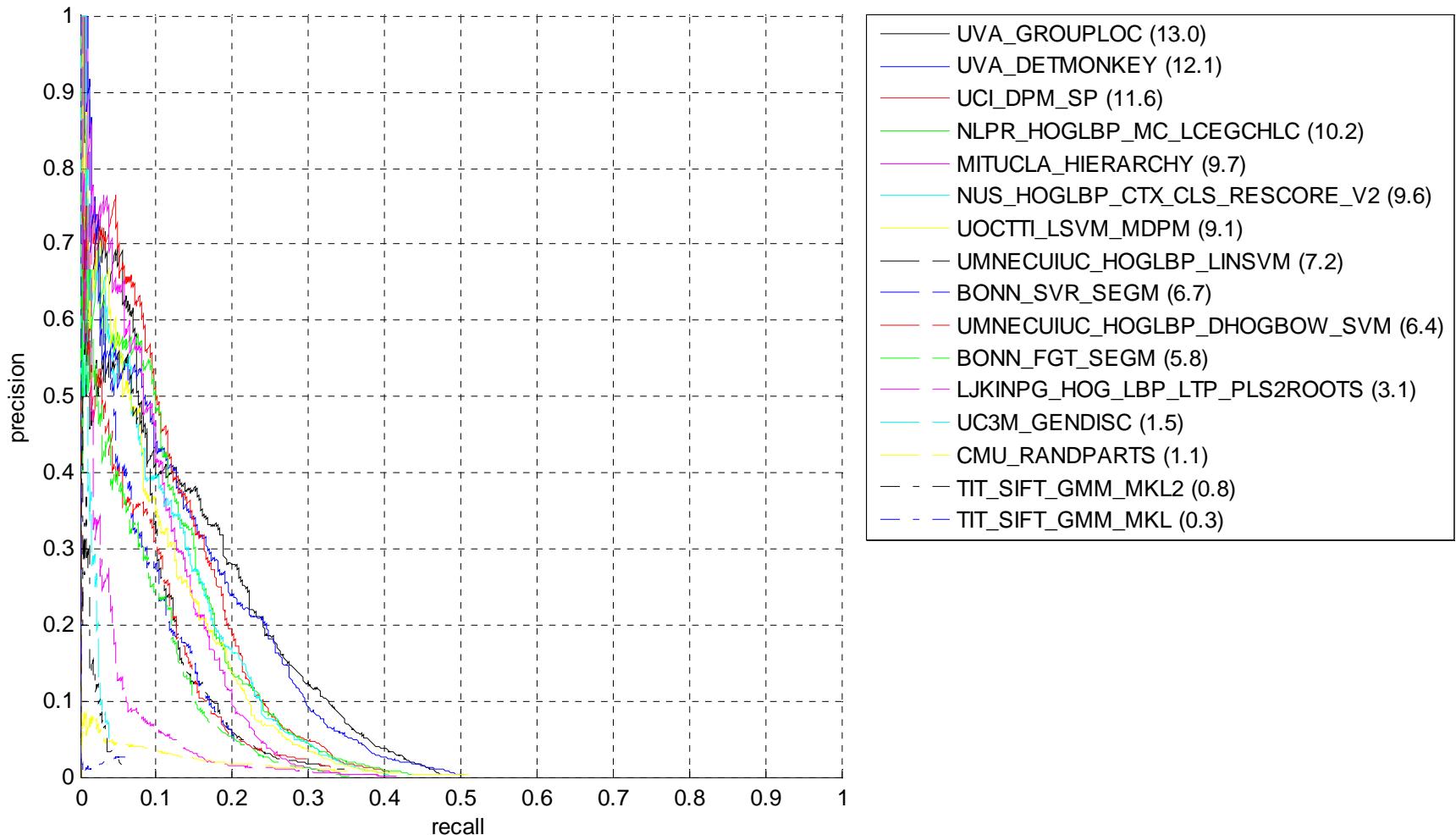
Precision/Recall - Bicycle



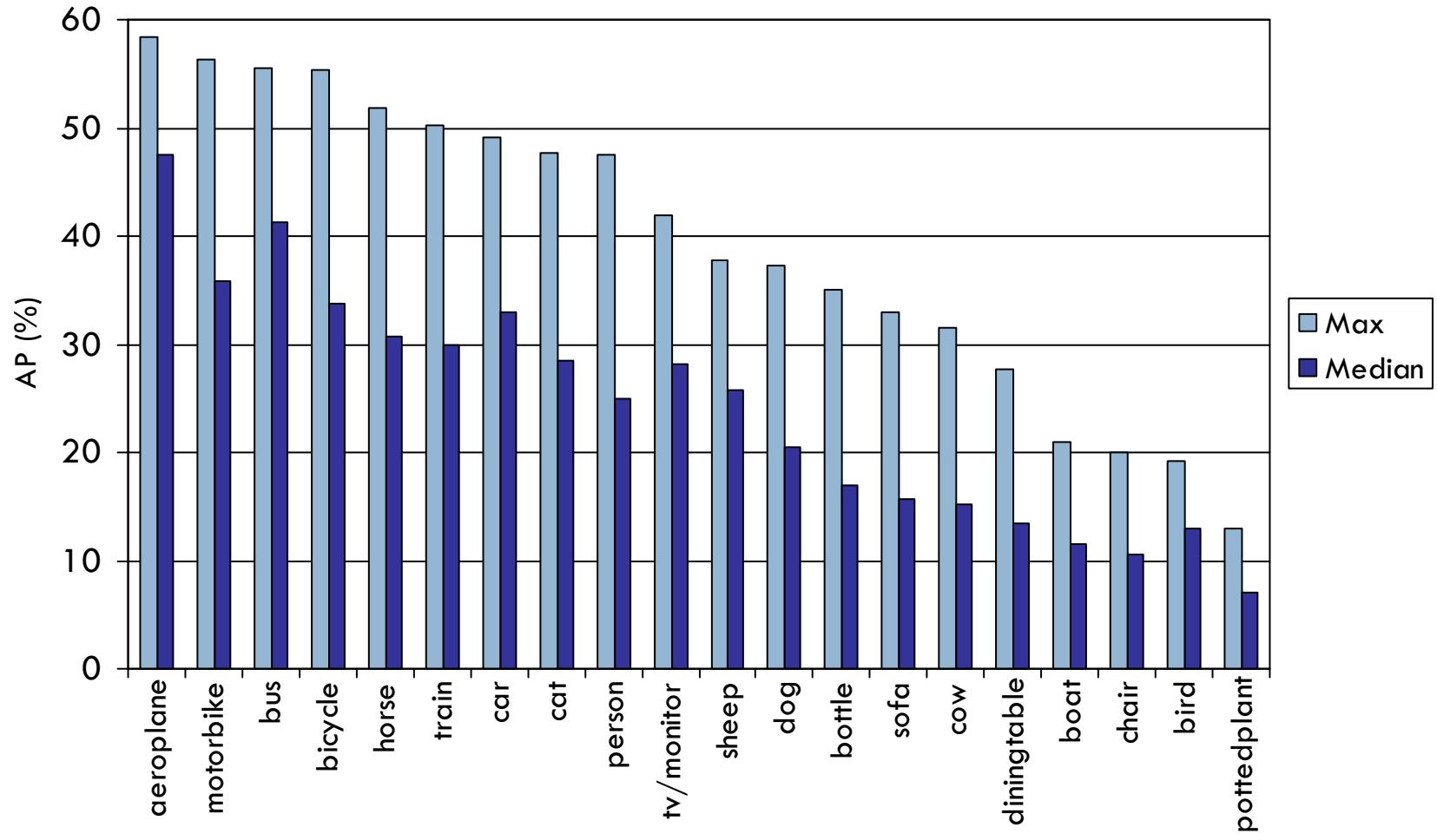
Precision/Recall - Car



Precision/Recall – Potted plant

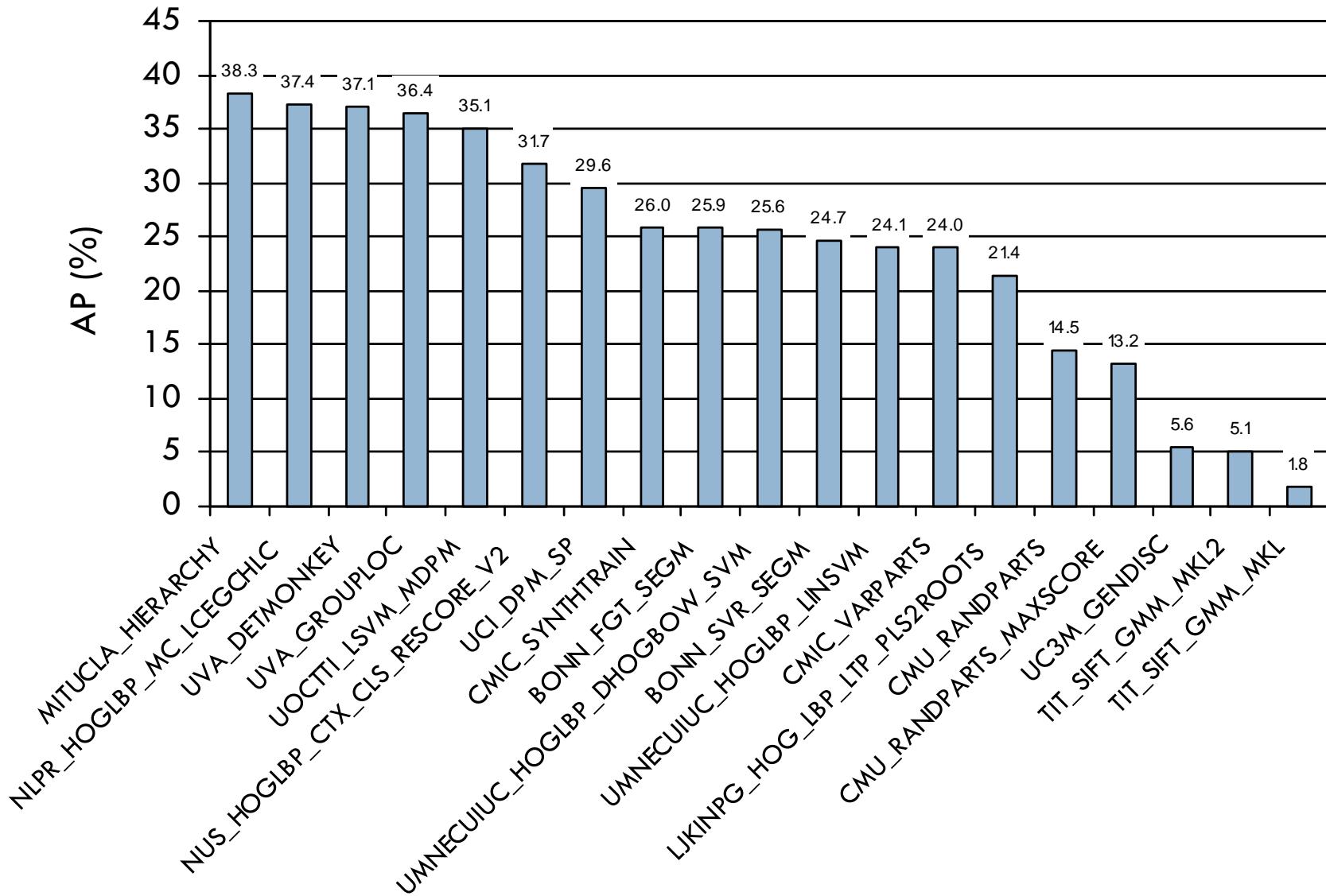


AP by Class



- Max AP: 58.4% (aeroplane) ... 13.0% (potted plant)

Median AP by Method



True Positives - Person

UOCTTI_LSVM_MDPM



NLPR_HOGLBP_MC_LCEGCHLC



NUS_HOGLBP_CTX_CLS_RESCORE_V2



False Positives - Person

UOCTTI_LSVM_MDPM



NLPR_HOGLBP_MC_LCEGCHLC



NUS_HOGLBP_CTX_CLS_RESCORE_V2



“Near Misses” - Person

UOCTTI_LSVM_MDPBM



NLPR_HOGLBP_MC_LCEGCHLC

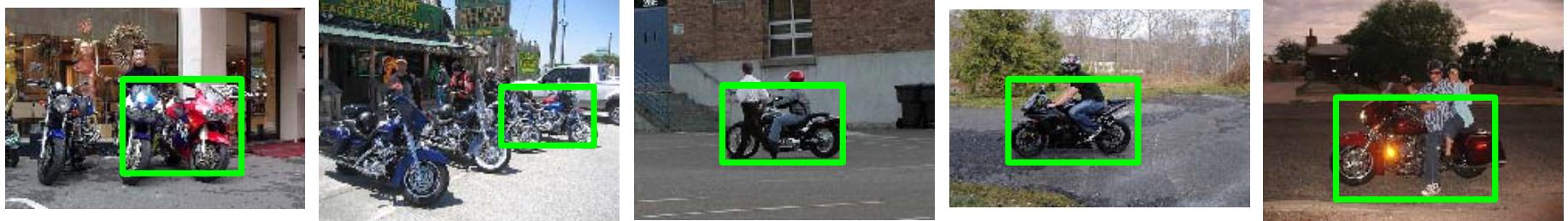


NUS_HOGLBP_CTX_CLS_RESCORE_V2



True Positives - Motorbike

MITUCLA_HIERARCHY



NLPR_HOGLBP_MC_LCEGCHLC



NUS_HOGLBP_CTX_CLS_RESCORE_V2



False Positives - Motorbike

MITUCLA_HIERARCHY



NLPR_HOGLBP_MC_LCEGCHLC



NUS_HOGLBP_CTX_CLS_RESCORE_V2



True Positives - Cat

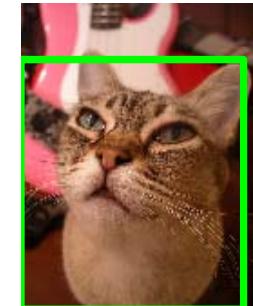
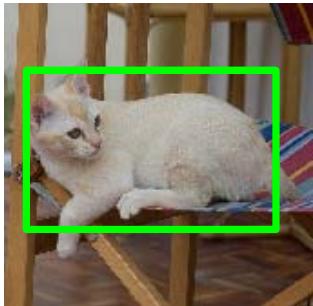
UVA_DETMONKEY



UVA_GROUPLOC



MITUCLA_HIERARCHY



False Positives - Cat

UVA_DETMONKEY



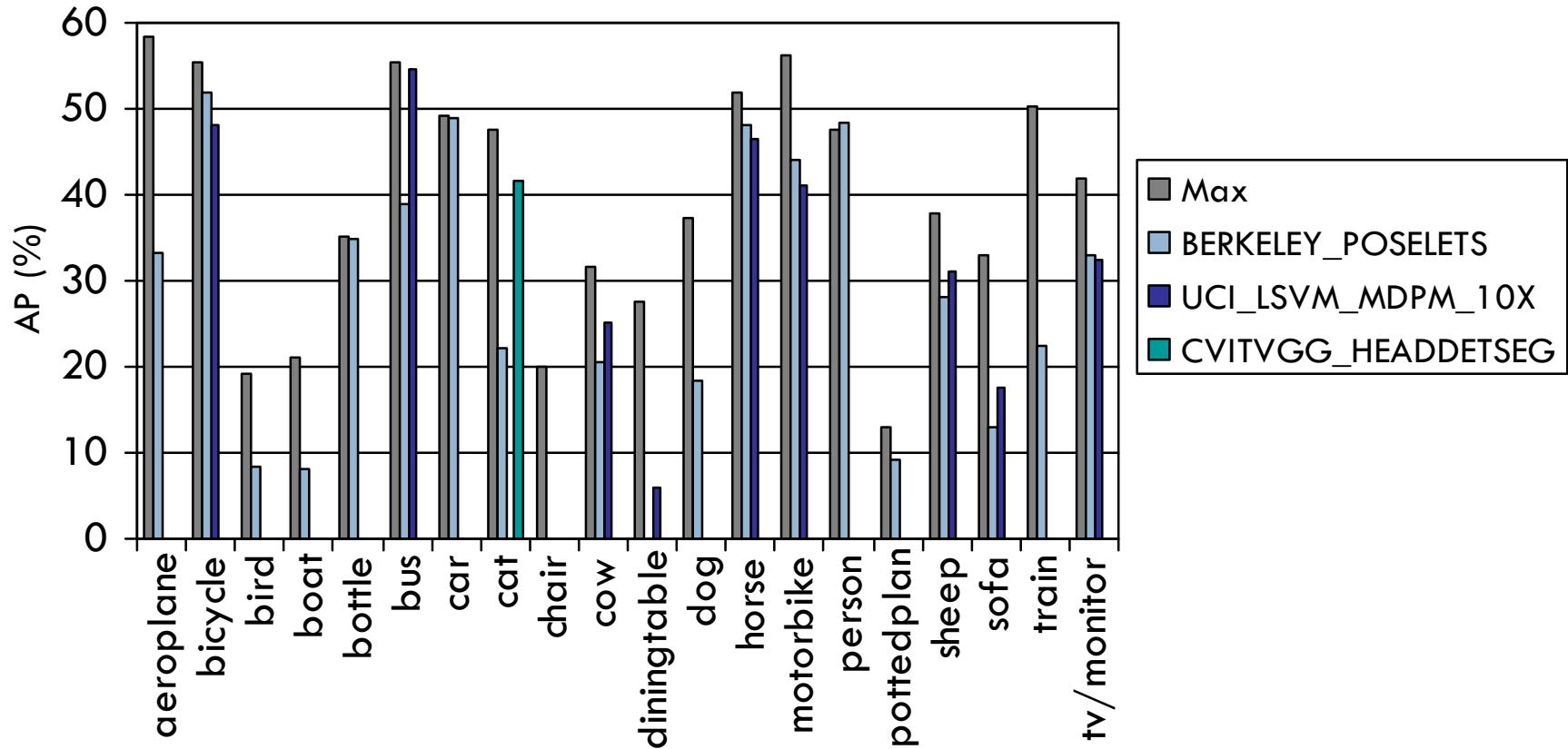
UVA_GROUPLOC



MITUCLA HIERARCHY

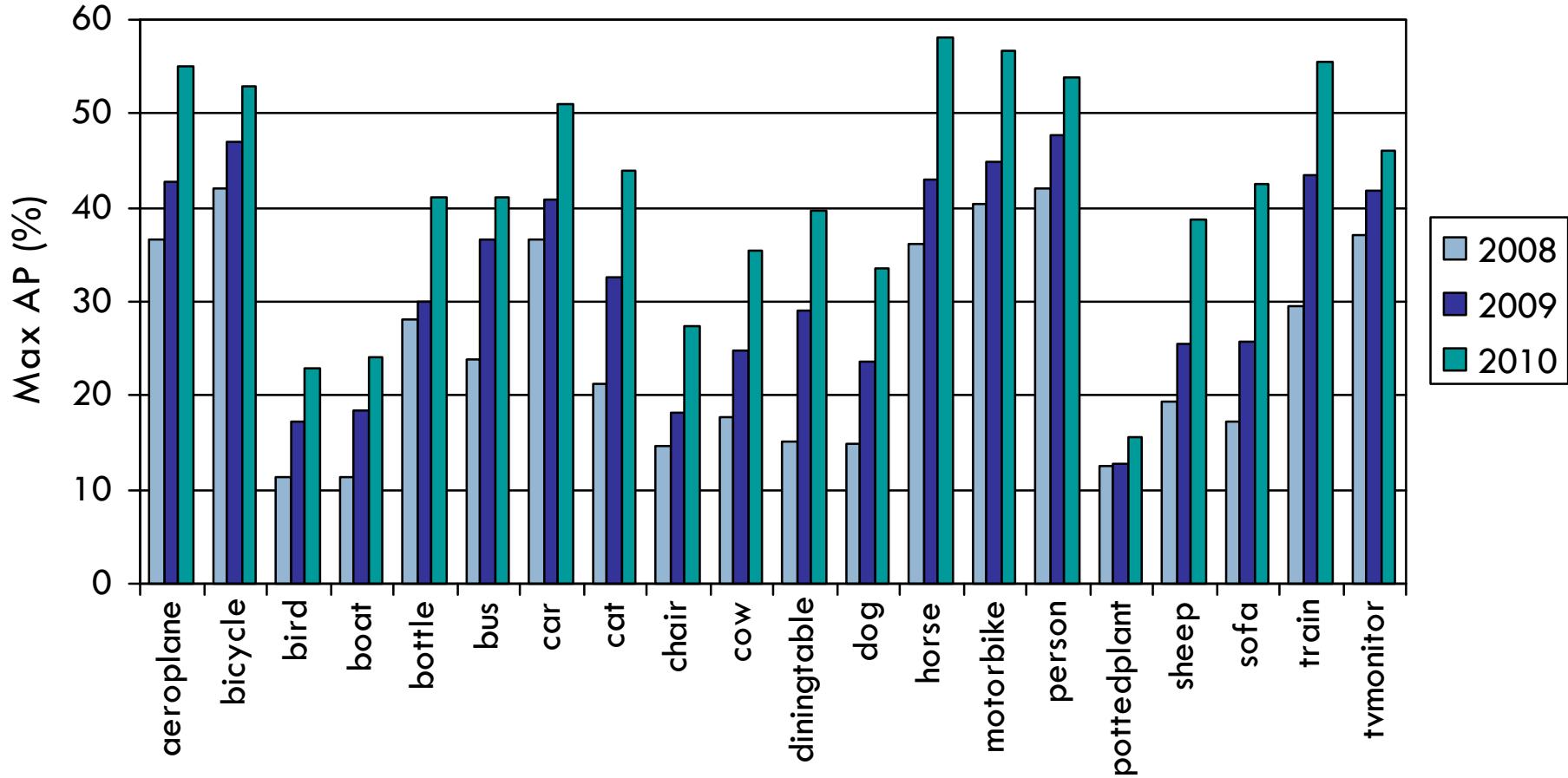


Additional Training Data/Annotation



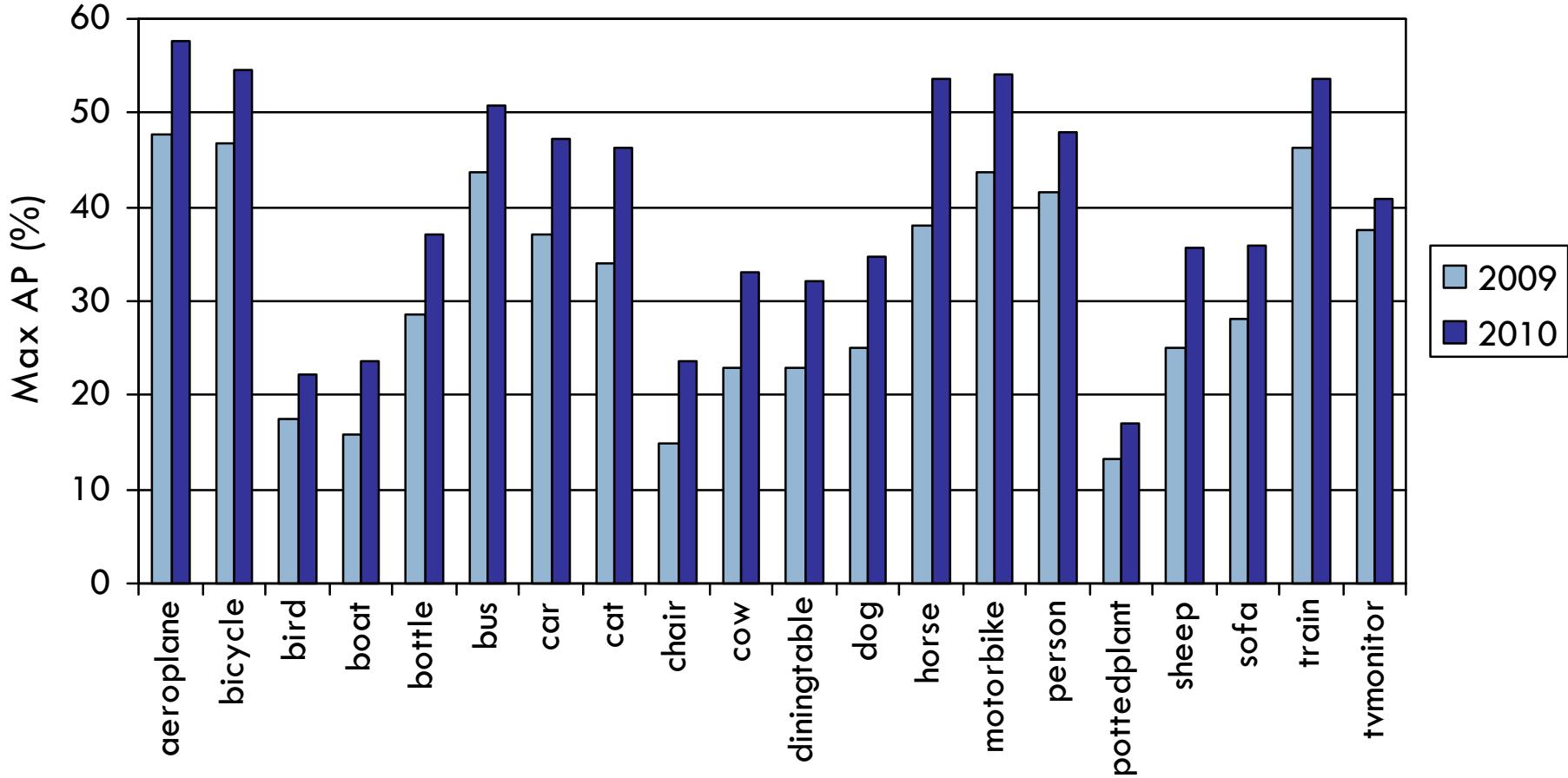
- BERKELEY use additional training data and annotation (manually labelled key points). Improves on best results for “person” class alone (1%).
- UCI annotated 10 times bigger training sets for some classes using Mechanical Turk. Does not improve on best results.
- CVIT/VGG used proprietary “cat” training set. Does not improve on best result.

Progress 2008-2010



- Results on 2008 data improve for best 2009 and 2010 methods for all categories, by over 100% for some categories
 - Caveat: Better methods or more training data?

Progress 2009-2010



- Best 2010 methods improve on 2009 results for all categories
 - Caveat: Better methods or more training data?

Prizes



- Winner:

- **NLPR_HOGLBP_MC_LCEGCHLC**

Yinan Yu, Junge Zhang, Yongzhen Huang, Shuai Zheng,
Weiqiang Ren, Chong Wang, Kaiqi Huang, Tieniu Tan
*National Laboratory of Pattern Recognition, Institute of
Automation, Chinese Academy of Sciences*

- Honourable Mentions:

- **MITUCLA_HIERARCHY**

Long Zhu, Yuanhao Chen, William Freeman, Alan Yuille,
Antonio Torralba
MIT, UCLA

- **NUS_HOGLBP_CTX_CLS_RESCORE_V2**

Zheng Song, Qiang Chen, Shuicheng Yan
National University of Singapore

- **UVA_GROUPLOC/UVA_DETMONKEY**

Jasper Uijlings, Koen van de Sande, Theo Gevers,
Arnold Smeulders, Remko Scha
University of Amsterdam

“Lifetime Achievement” Prize



- **UoC/TTI Chicago**

Pedro Felzenszwalb¹, Ross Girshick¹,
David McAllester², Deva Ramanan³

¹*University of Chicago*

²*Toyota Technological Institute at Chicago*

³*University of California, Irvine*

- First submitted to the PASCAL VOC challenge in 2007, this detector has now become a core component of many classification, segmentation, person layout and action classification submissions
- We honour the contribution made to the community by the innovation and success of the method and its free distribution