



Action Classification: An Integration of Randomization and Discrimination in A Dense Feature Space

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Visual Object Classes Challenge 2011 (VOC2011)



Outline

- Action Classification & Intuition
- Our Method
- Our Results
- Conclusion

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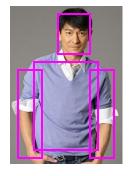






Object classification:









Presence of parts and their spatial configurations.

[Lazebnik et al, 2006] [Fergus et al, 2003]

. . .



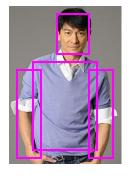




All images contain humans;

Object classification:









[Lazebnik et al, 2006] [Fergus et al, 2003]

Presence of parts and their spatial configurations.

5



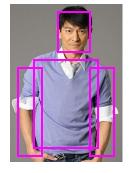




- All images contain humans;
- Large pose variation;

Object classification:









[Lazebnik et al, 2006] [Fergus et al, 2003]

Presence of parts and their spatial configurations.

6





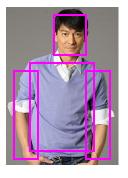


- All images contain humans;
- Large pose variations;
- Objects small or absent;
- Background clutter.

Challenging...

Object classification:









[Lazebnik et al, 2006] [Fergus et al, 2003]

Presence of parts and their spatial configurations.

7

Our Intuition



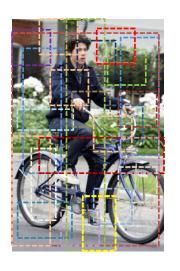


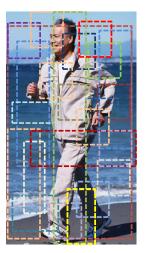


Focus on image regions that contain the most discriminative information.

Our Intuition







Focus on image regions that contain the most discriminative information.

How to represent the features?

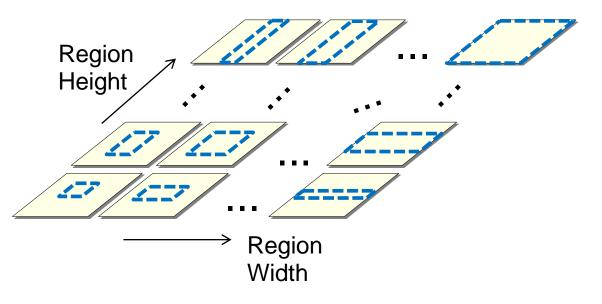
Dense feature space

How to explore this feature space?

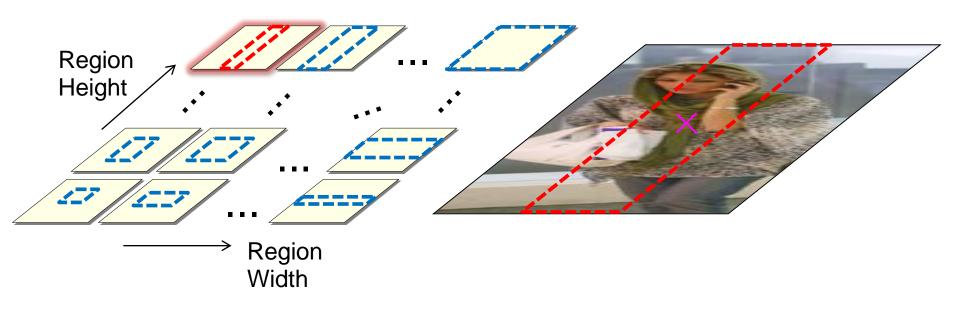
Randomization & Discrimination

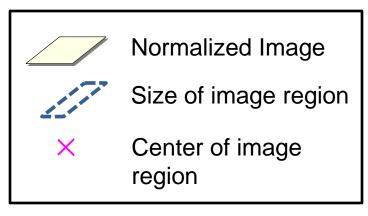
Outline

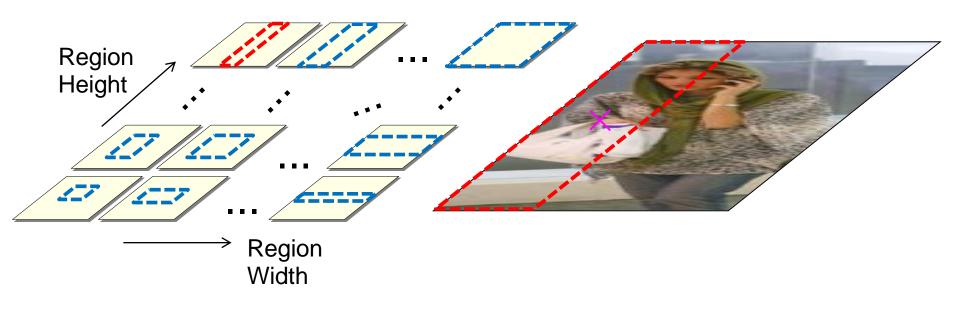
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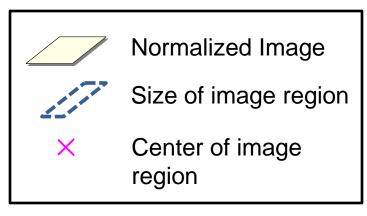


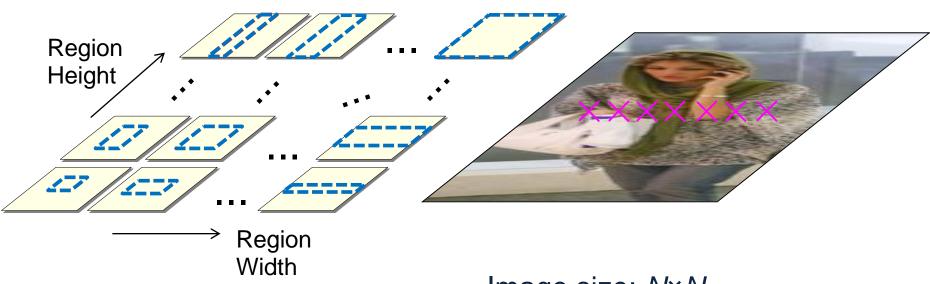












Normalized Image

Size of image region

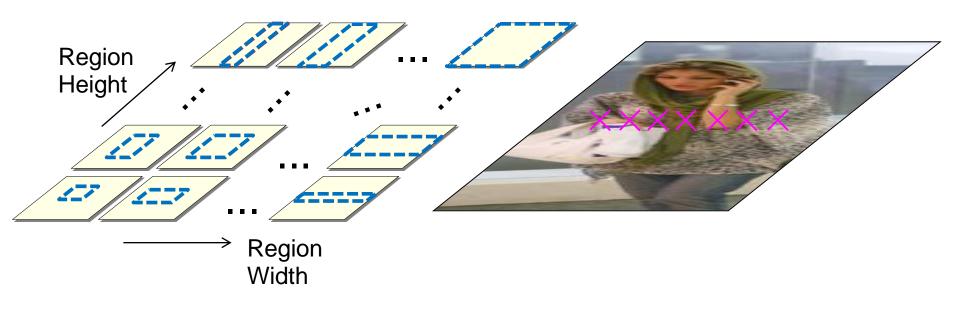
Center of image region

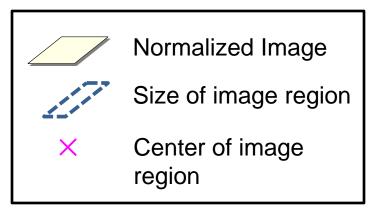
region

Image size: N×N

Image regions: $O(N^6)$

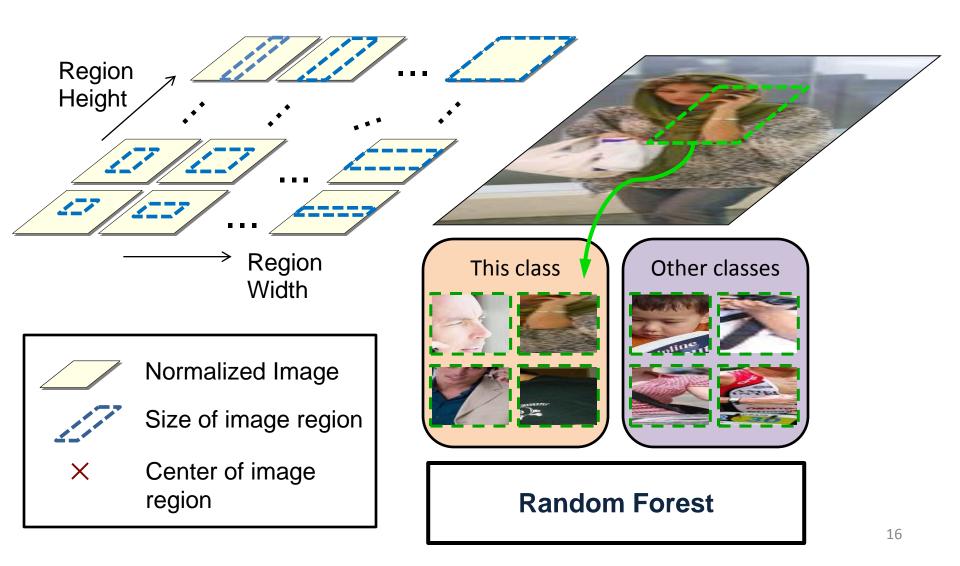
How can we identify the **discriminative** regions **efficiently** and **effectively**?

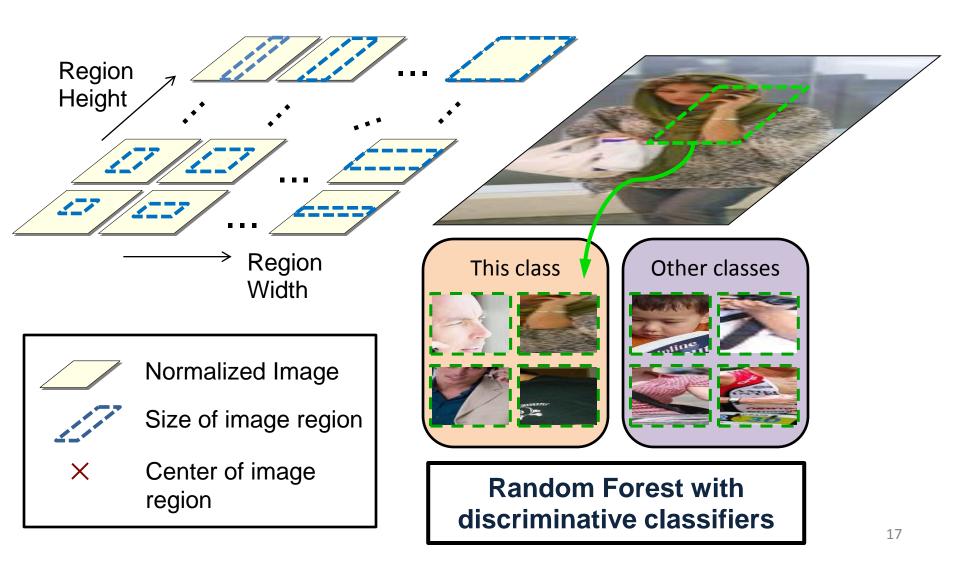




Apply randomization to sample a subset of image patches

Random Forest





Generalization of Random Forest

 Generalization error of a Random Forest (Breiman, 2001):

$$\rho \frac{(1-s^2)}{s^2}$$

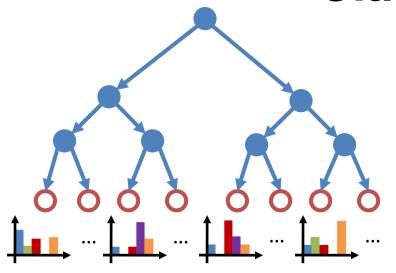
s: strength of the decision trees

 ρ : correlation between decision trees

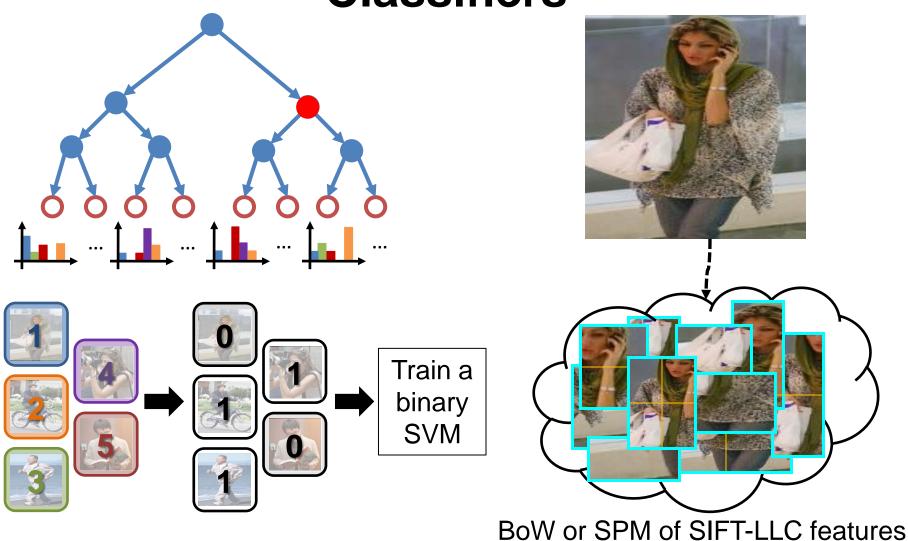


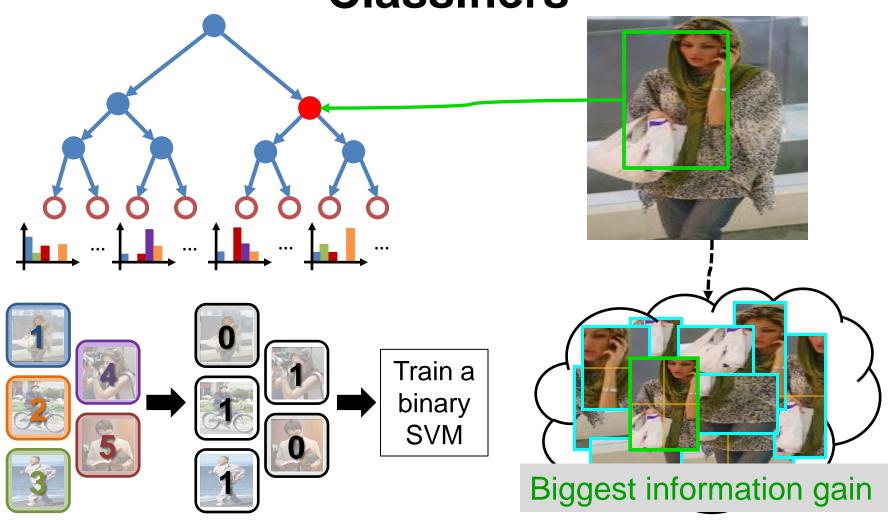
- Discriminative classifiers \longrightarrow S increases
- Dense feature space $\rightarrow \rho$ decreases

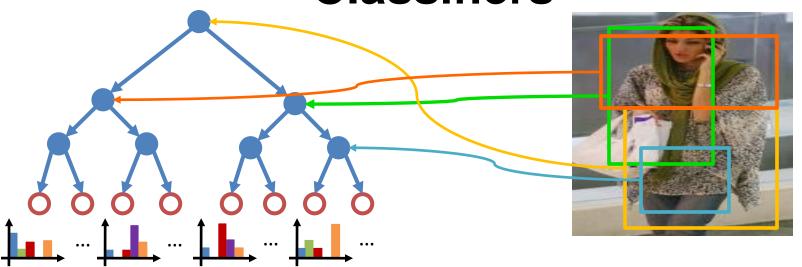


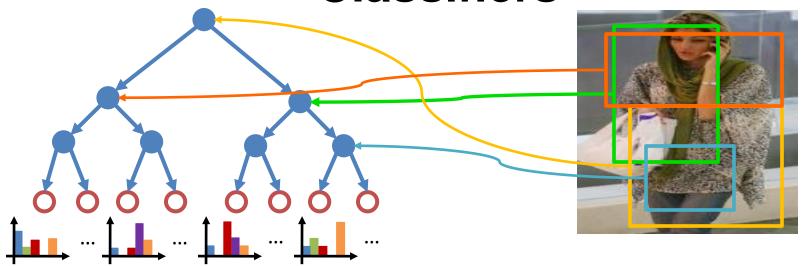






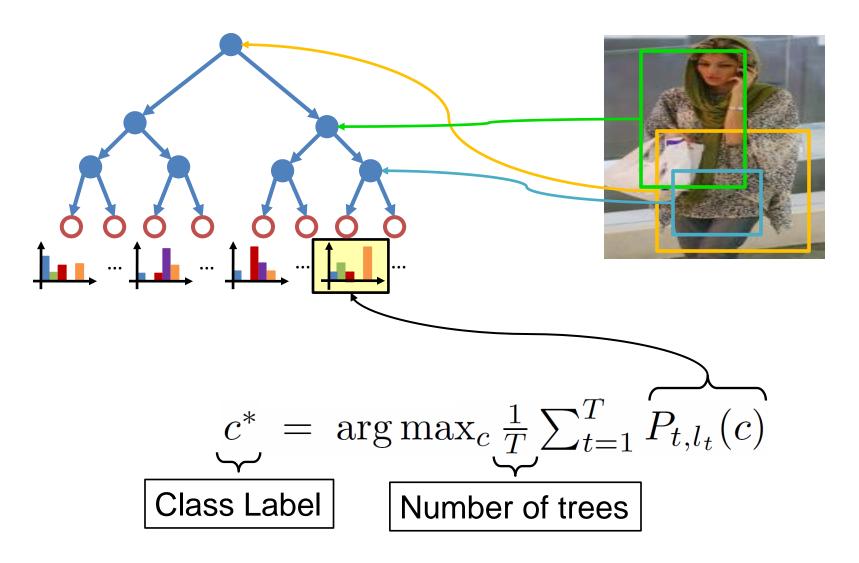






- We stop growing the tree if:
 - The maximum depth is reached;
 - There is only one class at the node;

Classification With Random Forest



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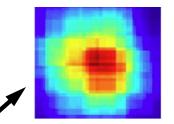
Results on VOC 2011 Action Comp9

Action	Others' Best	Our Method
Jumping	71.6	66.0
Phoning	50.7	41.0
Playing instrument	77.5	60.0
Reading	37.8	41.5
Riding bike	88.8	90.0
Riding horse	90.2	92.1
Running	87.9	86.6
Taking photo	25.7	28.8
Using computer	58.9	62.0
Walking	59.5	65.9

Our method ranks the first in **six** out of ten classes.

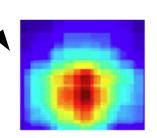
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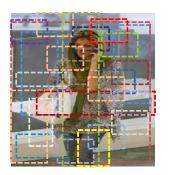


Generalization Ability of RF

Dense feature space
 Tree correlation decreases





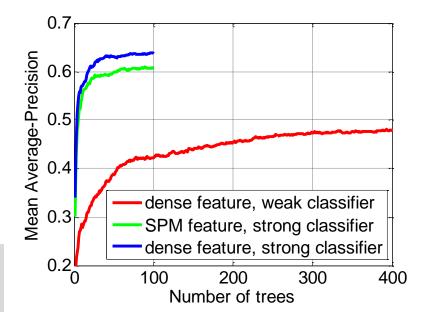


(spatial pyramid) **Vs.** dense feature SPM feature

Generate feature weights randomly

Train discriminative SVM classifiers

weak classifier **Vs.** strong classifier



(Results on PASCAL VOC 2010)

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Conclusion

- Exploring dense image features can benefit action classification;
- Combining randomization and discrimination is an effective way to explore the dense image representation;
- Achieves very good performance based on only one type of image descriptor;
- Code will be available soon.

PASCAL VOC 2011 Result Comp10

	Others' best	Our method
Jumping	59.5	66.7
Phoning	31.3	41.1
Playing instrument	45.6	60.8
Reading	27.8	42.2
Riding bike	84.4	90.5
Riding horse	88.3	92.2
Running	77.6	86.2
Taking photo	31.0	28.8
Using computer	47.4	63.5
Walking	57.6	64.2

Wednesday 9th November, 12:00-12:30

Acknowledgement



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Reference:

Bangpeng Yao, Aditya Khosla, and Li Fei-Fei. "Combining Randomization and Discrimination for Fine-Grained Image Categorization." CVPR 2011.