# Segmentation \& Layout Taster Competitions 

PASCAL Visual Object Classes 2007




## Segmentation taster results

## Evaluation: average \% accuracy across all classes.

|  | mea | back- <br> ground | $\begin{aligned} & \text { aero- } \\ & \text { plane } \end{aligned}$ | bicycle | bird | boat | bottle | bus | car | cat | chair | cow | dining table | dog | horse | $\underset{\substack{\text { motor- } \\ \text { bike }}}{\text { m- }}$ | person | $\begin{gathered} \text { potted } \\ \text { plant } \end{gathered}$ | sheep | sofa | train | $\begin{gathered} \text { tvl } \\ \text { monitor } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Brookes | 8.5 | 77.7 | 5.5 | 0.0 | 0.4 | 0.4 | 0.0 | 8.6 | 5.2 | 9.6 | 1.4 | 1.7 | 10.6 | 0.3 | 5.9 | 6.1 | 28.8 | 2.3 | 2.3 | 0.3 | 10.6 | 0.7 |
| INRIA Normal* | 7.7 | 2.8 | 1.2 | 1.8 | 8.3 | 1.5 | 52.4 | 0.3 | 12.4 | 5.3 | 3.7 | 0.0 | 18.3 | 4.1 | 0.1 | 0.1 | 3.6 | 28.7 | 0.3 | 6.1 | 0.4 | 10.6 |
| INRIA <br> PlusClass* | 23.5 | 2.9 | 0.6 | 44.8 | 34.4 | 16.4 | 19.9 | 0.4 | 68.0 | 58.1 | 10.5 | 0.4 | 43.5 | 7.7 | 0.9 | 1.7 | 59.2 | 37.2 | 0.0 | 5.5 | 19.0 | 63.2 |
| $\begin{array}{r} \text { MPI } \\ \text { Center* } \end{array}$ | 17.5 | 56.6 | 11.8 | 31.2 | 0.0 | 11.0 | 0.0 | 0.1 | 35.7 | 51.4 | 7.3 | 20.3 | 0.0 | 1.0 | 2.3 | 2.6 | 60.0 | 0.0 | 2.6 | 5.0 | 43. | 25.3 |
| $\begin{array}{r} \text { MPI } \\ \text { ESSOL* } \end{array}$ | 27.8 | 2.6 | 29.7 | 30.8 | 9.5 | 41.4 | 6.7 | 8.0 | 72.9 | 55.7 | 37.1 | 11.1 | 19.4 | 2.2 | 14.9 | 23.8 | 66.8 | 25.9 | 8.6 | 3.2 | 58.1 | 55.1 |
| TKK* | 30.4 | 22.9 | 18.8 | 20.7 | 5.2 | 16.1 | 3.1 | 1.2 | 78.3 | 1.1 | 2.5 | 0.8 | 23.4 | 69.4 | 44.4 | 42.1 | 0.0 | 64.7 | 30.2 | 34.6 | 89.3 | 70.6 |
| Jo | 21.2 | 2.5 | 24.1 | 52.5 | 0.4 | 1.6 | 16.4 | 9.4 | 32 | 1.0 | 5.5 | 9.5 | 0.1 | 0.2 | 2.7 | 20.9 | 60.2 | 11.4 | 0.0 | 25 | 71.7 | 57.5 |

*Automatic entry from detection competition entry


- Winner: Helsinki University of Technology (TKK)
- Honourable mention: Oxford Brookes


## Discussion questions

- Evaluation metric
- Percentage accuracy overall/average per-class
- Intersection/union measure

$$
=\frac{\text { true pos. }}{\text { true pos. }+ \text { false pos. }+ \text { false neg. }}
$$

- Selection of classes
- Same as for detection challenge (allows entry for both)
- Fewer classes (more training data per class)
- Also allow 'stuff' e.g. sky, grass
- Other suggestions?


## Person layout training data



- Subset of "person" objects annotated with bounding boxes of head, hands, feet

| Data set sizes: | Training | Validation | Total |
| :--- | :---: | :---: | :---: |
| Images | 166 | 156 | 322 |
| Objects | 220 | 219 | 439 |



## Discussion questions

- Evaluation metric
- Average precision (AP)
- Correct detection required correct prediction of all parts' presence/absence and bounding boxes
- Submitted method had $A P=0$ : Is this is a reasonable/sensitive evaluation measure?
- Participation
- Only one result submitted - is there interest in this task, is data seen as too difficult...?
- Other suggestions?

