

# Combining local and global Bag-of-Words representations for semantic segmentation.



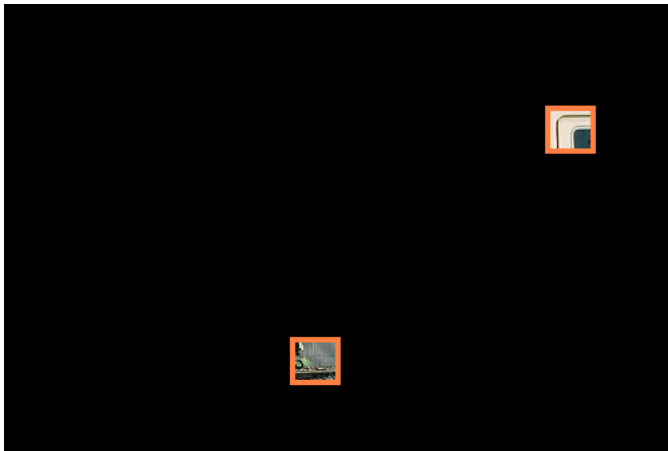
**UAB**  
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Centre de Visió per Computador



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A. Bagdanov	M. Pedersoli	J. González	J. Serrat

## Motivation



What's inside a local segment?

## Motivation



...and with context? [Fulkerson|CCV09]

# Motivation

Global classifier



What's inside a local segment?



## Contributions

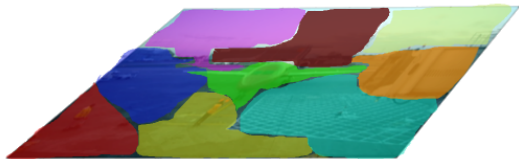
- Novel segmentation method that jointly uses global and local information.
- Concatenating the description of a superpixel and its context.
- Learn a per class normalization of the classification scores.

# Model



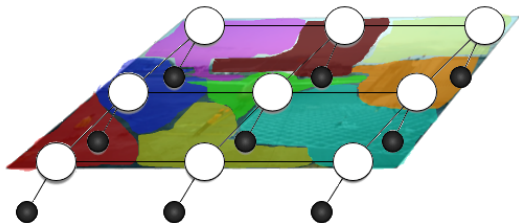
- **Original Image**
- Unsupervised Segmentation
- Superpixel Nodes
- Global Node
- Local Classification
- Global Classification
- Inference with Graph-Cuts

# Model



- Original Image
- **Unsupervised Segmentation**
- Superpixel Nodes
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- Local Classification
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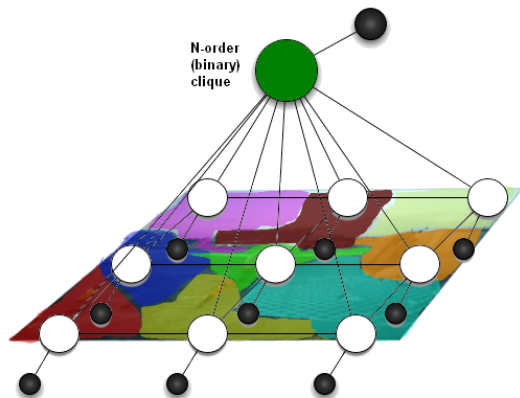
# Model



- Original Image
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- **Superpixel Nodes**
- Global Node
- Local Classification
- Global Classification
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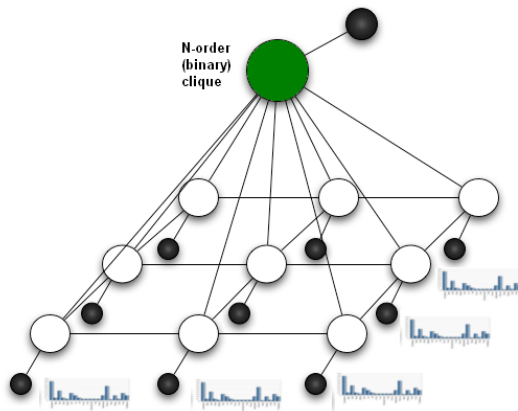


# Model



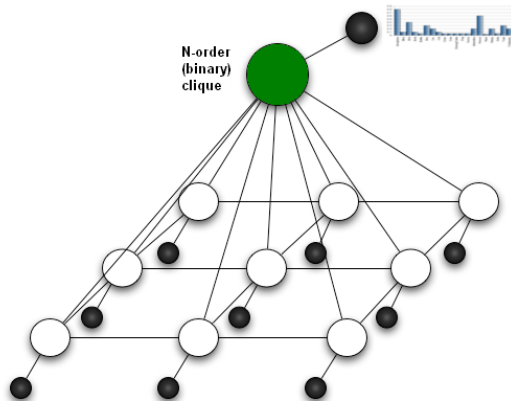
- Original Image
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# Model



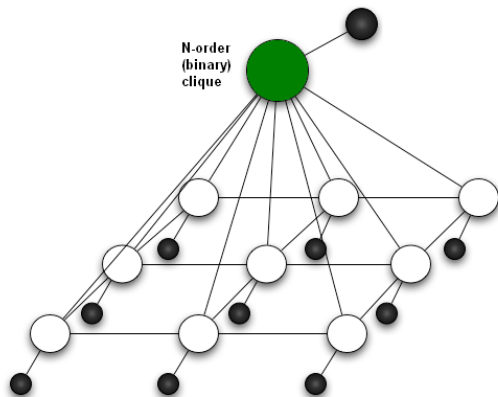
- Original Image
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- **Local Classification**
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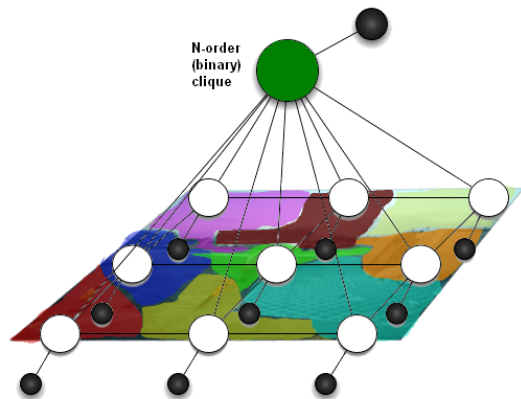
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- **Global Classification**
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# Model



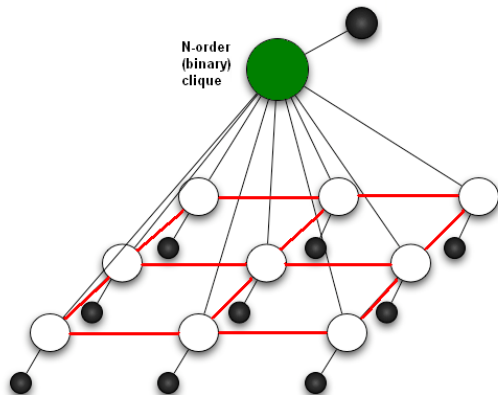
- Original Image
- Unsupervised Segmentation
- Superpixel Nodes
- Global Node
- Local Classification
- Global Classification
- **Inference with Graph-Cuts**

# Model



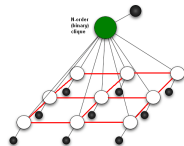
$$\sum_{s \in \mathcal{S}} \text{local} + \sum_{(p,q) \in \mathcal{N}_s} \text{smoothness} + \sum_{g \in \mathcal{G}} \text{global} + \sum_{(p,q) \in \mathcal{N}_{sg}} \text{consistency}$$

## Smoothness term



$$\sum_{s \in \mathcal{S}} \text{local} + \sum_{(p,q) \in \mathcal{N}_s} \text{smoothness} + \sum_{g \in \mathcal{G}} \text{global} + \sum_{(p,q) \in \mathcal{N}_{sg}} \text{consistency}$$

## Smoothness term

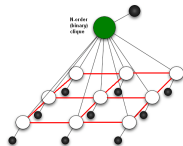


$$\text{smoothness}(s_i, s_j, c_{ij}) = \lambda \theta(c_{ij}) N_{ij} \delta(s_i, s_j)$$



- PixelLevel
- Oversegmentation
- Modulated Potts
- Color conditioned

## Smoothness term



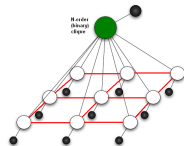
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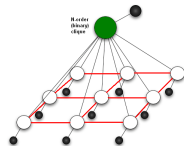


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# Smoothness term

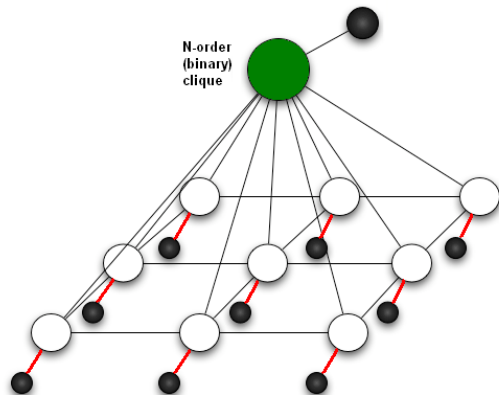


$$\text{smoothness}(s_i, s_j, c_{ij}) = \lambda \theta(c_{ij}) N_{ij} \delta(s_i, s_j)$$



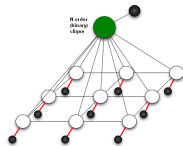
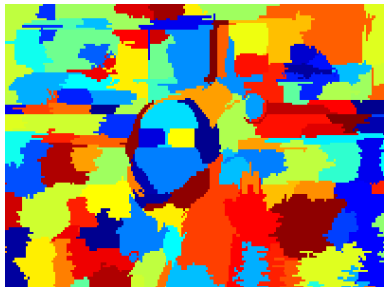
- Pixel level
- Oversegmentation
- Modulated Potts
- **Color conditioned**

## Local term



$$\sum_{s \in \mathcal{S}} \text{local} + \sum_{(p,q) \in \mathcal{N}_s} \text{smoothness} + \sum_{g \in \mathcal{G}} \text{global} + \sum_{(p,q) \in \mathcal{N}_{sg}} \text{consistency}$$

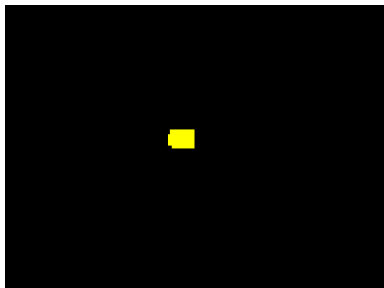
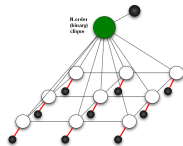
## Local term



## Bag-of-Words:

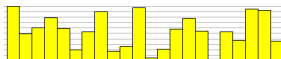
- Inside Region (20%)
- Contextual Regions (27%)
- Concatenate Both Regions (29%)

# Local term

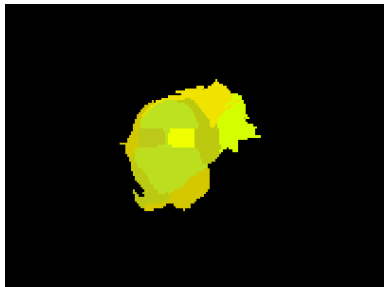
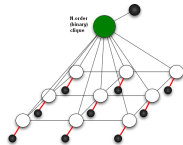


## Bag-of-Words:

- **Inside Region (20.02%)**
- Contextual Regions (27%)
- Concatenate Both Regions (29%)

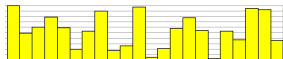


# Local term

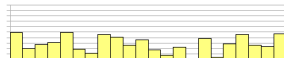


## Bag-of-Words:

- Inside Region (20%)
- **Contextual Regions (27.14%)**
- Concatenate Both Regions (29%)

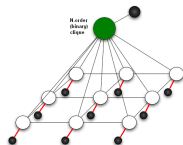


+





## Local term



Detector:

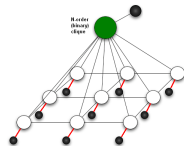
- Dense Grid with 50% of overlapping between patches.
- 4 different scales.

Description:

- Shape feature: SIFT. (28.34%)
- Color feature: RGB Histogram. (22.5%)
- Concatenate SIFT + Color histogram. (29.53%)



## Local term

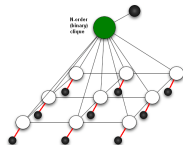


- 20 SVM with Intersection Kernel.
- 20.000 training samples for each class.



One class against all classes.

## Local term

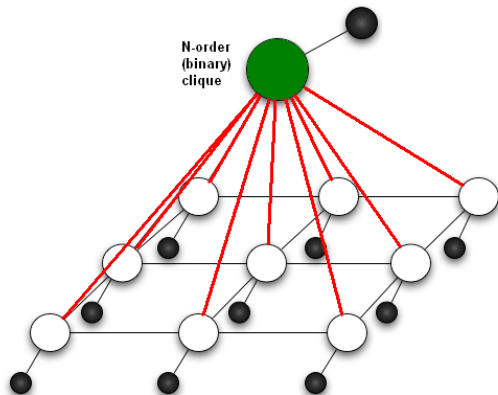


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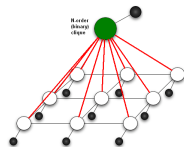
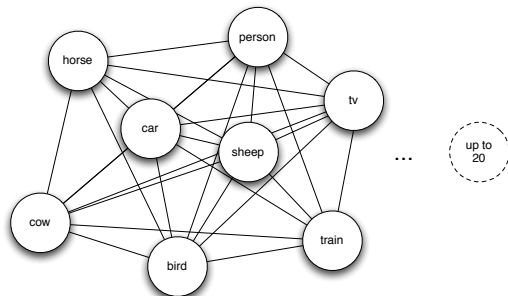
One class against its background. Similar to [CsurkaBMCV08].

## Consistency term



$$\sum_{s \in \mathcal{S}} \text{local} + \sum_{(p,q) \in \mathcal{N}_s} \text{smoothness} + \sum_{g \in \mathcal{G}} \text{global} + \sum_{(p,q) \in \mathcal{N}_{sg}} \text{consistency}$$

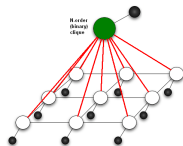
## Consistency term



- $g_i \in \{0, 1\}$
- All global nodes are connected to each superpixel node.

$$\text{consistency}(s_i, \mathcal{G}) = \beta M_i \prod_{g_j=1 \in \mathcal{G}} (1 - \delta(s_i, j))$$

## Consistency term

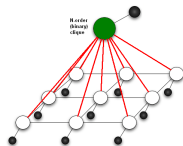


Equivalent problem:

- Substitute  $g_i$  with ONE node  $g \in \{\mathcal{L}_{comb}\}$ .
- Each label in  $\{\mathcal{L}_{comb}\}$  represents a **combination** of classes in the image.
- Thus,  $g$  has a total amount of  $2^N$  possible labels.

Too many labels to be solvable in reasonable time.

## Consistency term

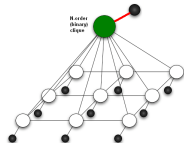


Approximate problem:

- Use only the most likely  $\mathcal{L}_{comb}$ :
  - Discard objects with very low global classification rate ( $\leq 0.05$ ).
  - Possible combinations of objects in the same image.
- Solvable with standard graph-cuts (less than 2 seconds).

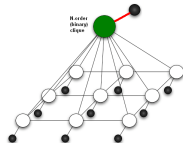


# Global term





# Global term



## Feature Detection



Grid Sampling



Harris-Laplace



Boosted Harris-Laplace



Blob detector



Boosted Blob detector

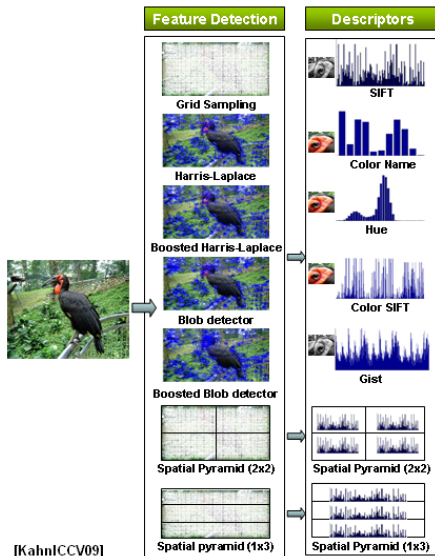
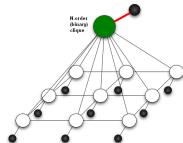


Spatial Pyramid (2x2)

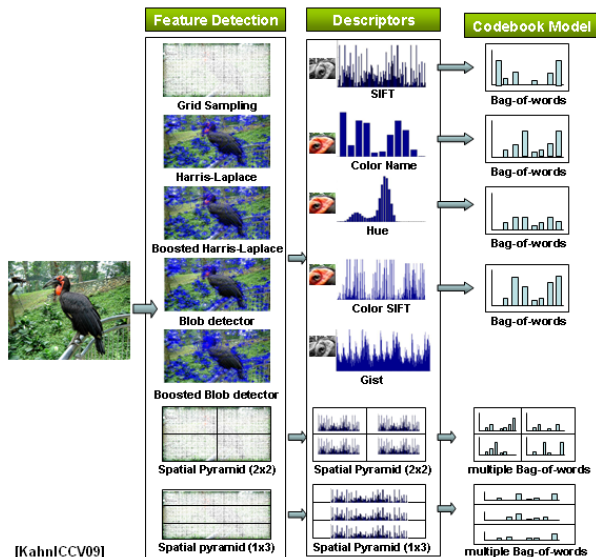
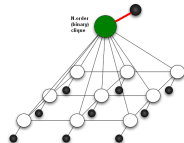


Spatial pyramid (1x3)

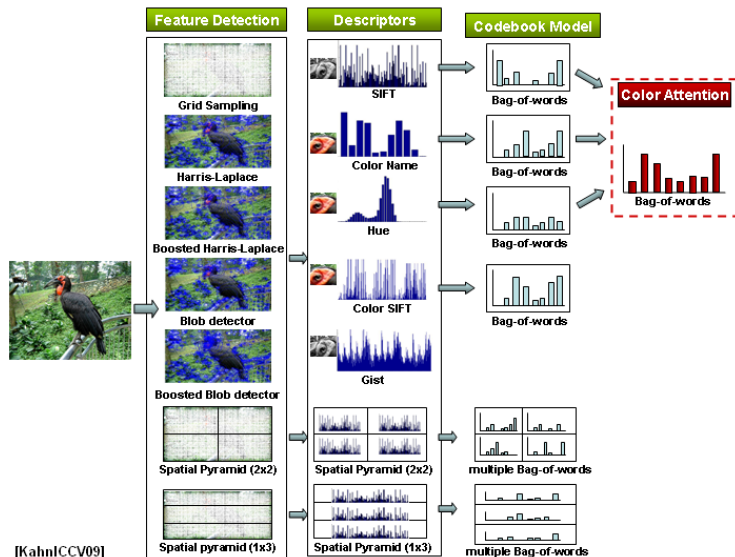
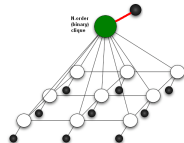
# Global term



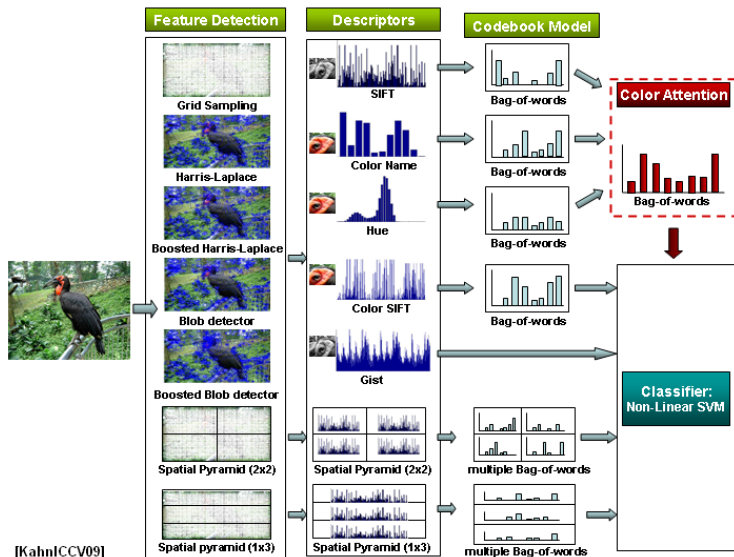
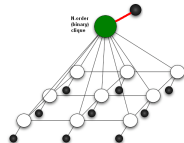
# Global term



# Global term



# Global term



## Learning the parameters

- The best configuration maximizes the geometric mean of the performance of all classes.
- We obtain new configurations in a **Gibbs sampler** manner:

$$x_i^{t+1} \sim \mathcal{N}(x_i^t, f(t))$$

- 2-fold cross validation.
- Learning stages:
  - 1 Weights of the graphical model. (29.53%)
  - 2 Per class normalization of the local term. (31.25%)
  - 3 Per class normalization of the global term. (35.1%)

## Conclusions

- We propose a novel segmentation method that jointly uses global and local information.
- Using as negative examples only the segments that appear in the same image of positive samples decreases the variability of the data.
- Concatenating both the description of a superpixel and its context is helpful for classification. (+2.5%)
- We empirically prove that a per class normalization of the observed terms is able to efficiently equalize classification scores. (+5.6%)

Gràcies!

Thank you!

Arigato!



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